# Runsong Zhu

(+86) 183-7315-0759 · zhurunsong@whu.edu.cn

#### **EDUCATION**

Wuhan University

Sept 2019 - Present

M. Eng. in Surveying and Mapping Engineering, Grade: 83/100

Central South University

Sept 2015 - Jun 2019

B. Sc. in Geographic Information Science (GIS), Grade: 87/100 (rank 4 out of 47)

### INTERNSHIP

Tencent AI-Lab

Jun 2021 - Present

Working on surface reconstruction from multi-view images; Supervised by Dr. Di Kang and Dr. Linchao Bao

**DiDi**Jun 2020 - Sept 2020

Worked on real-time bus trajectory data processing and data mining.

Chuangxin Deecamp Jun 2019 - Aug 2019

Worked on financial time series data analysis and forecasting; Supervised by Dr. Ji Feng

Baidu Map

Jun 2018 - Oct 2018

Worked on the development of android test platform for "BaiduMap" APP.

# RESEARCH PROJECTS

Research Interests: 3D Vision, Point Cloud Processing, Computer Graphics, Deep Learning, etc.

# **Human face reconstruction from limited number images (on-going)**

- Aiming to efficiently and accurately extract the underlying 3D geometry from given limited number of facial images as input
- Proposing a progressive method to optimize the SDF model from a coarse-refine structure, which not only accelerates the training speed but also improves the final reconstruction quality.

#### Robust normal estimation for point cloud

- Aiming to accurately estimate point-wise normal vector of an input point set.
- Tackled several challenges including noisy input, severe outliers, uneven sampling density, etc.
- Outperformed DeepFit and achieved state-of-the-art performance on the PCPNet dataset (synthetic) and SceneNN dataset (real-world)
- Work accepted to ICCV 2021(first author, oral)

#### Heat leakage detection by fusion of point cloud and infrared image

- Aiming to analyze the heat information around windows to detect the heat leakage, by utilizing multimodal data including point clouds and infrared images.
- Applying *harris\_2d* operator (on images) and *harris\_3d* operator (on point clouds) to find corner points, which are used to register the input images and point clouds via RANSAC.
- Achieving heat leakage detection by analyzing the temperature difference between the walls and the windows, which are determined in 3D from the 2D detection.

#### Semantics and topology representation of residential buildings

- Proposed a novel and fully automatic method to get meaningful semantics and topology representation of residential-building space using floor-plan raster maps
- Submitted to IEEE TGRS (under-view)

# **Segmentation for large-scale point clouds**

- Designed a novel convolutional operator to process point cloud for semantic segmentation, where points are processed directly and converted to voxels simultaneously
- Work accepted to Journal of Wuhan University 2020

# **PUBLICATION**

- 1. Rethinking Learning-based Normal Estimation on Point Clouds

  Runsong Zhu, Liu Yuan (equal contribution), Zhen Dong, Tengping Jiang, Yuan Wang, Wenping Wang, Bisheng Yang.
- 2. Automated semantics and topology representation of residential-building space using floor-plan raster maps.

  \*Under review\*\*

Bisheng Yang, Tengping Jiang, Weitong Wu, Runsong Zhu, Yuzhou Zhou, Lei Dai

3. Bievel Convolutional Neural Networks for 3D Semantic Segmentation Using Large-scale LiDAR Point clouds in Complex Environments

Journal of Wuhan University, 2020
Tengping Jiang, Bisheng Yang, Yuzhou Zhou, Runsong Zhu, Zhen Dong.

#### **AWARDS**

- 2020 Lidar Congress Point Cloud Segmentation Track (First Prize)
- 2019 Unique hackday (Best Technology Award)
- 2019 National GIS Development Competition (First Prize)
- 2018 Mathematical Contest In Modeling (Meritorious Winner)

#### PROFESSIONAL SKILLS

Programming languages: Python, Java, Matlab, C/C++

Toolkits: Pytorch, OpenGL

Languages: Mandarin (native), English (fluent)